



# U.S. ARMY COMBAT CAPABILITIES DEVELOPMENT COMMAND – ARMY RESEARCH LABORATORY

Algorithmically identifying strategies in multi-agent game-theoretic environments

Erin Zaroukian

Cognitive Scientist

Social Terrain Modeling Team, Multilingual Computing and Analytics Branch, Computational and Information Sciences Directorate

DISTRIBUTION UNLIMITED



# INTRODUCTION



- Computational agents should support their human teammates by adapting their behavior to the humans' strategy for a given task in order to facilitate mutually-adaptive behavior within the team.
- While there are situations where human strategies are top-down, explicit, and easy to understand, human strategies are often implicit and *ad hoc*.



- Our goal: Identify and label the implicit human strategies  
→ Facilitate transparency, promote trust, and provide a better understanding of how humans work together and how computational teammates can be trained to fit into a human-human dynamic.



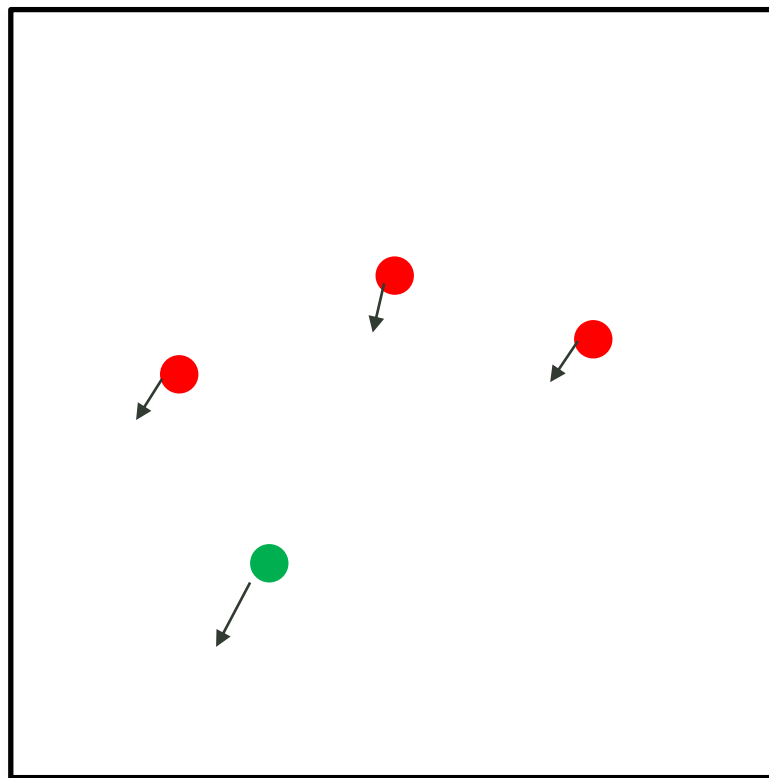
## STRATEGIES IN MOVEMENT DATA



- **Strategies aren't observable! Infer through measurements of behaviors toward a goal.**
- **Existing methods for identifying strategies often require:**
  - Verbal reports of strategy
  - *A priori* set of strategies to recognize
    - e.g., RElative MOtion
  - *A priori* chunking / atomic units of movement data (usually in highly constrained environments)
    - e.g., Context Free Grammars, Linear Temporal Logic
  - Repetition
    - e.g., ALCAMP
- **We use timeseries techniques**
  - Univariate measure of group configuration – *polygon area*
  - Identify strategies through Change Point Detection (CPD) and Dynamic Time Warping (DTW)

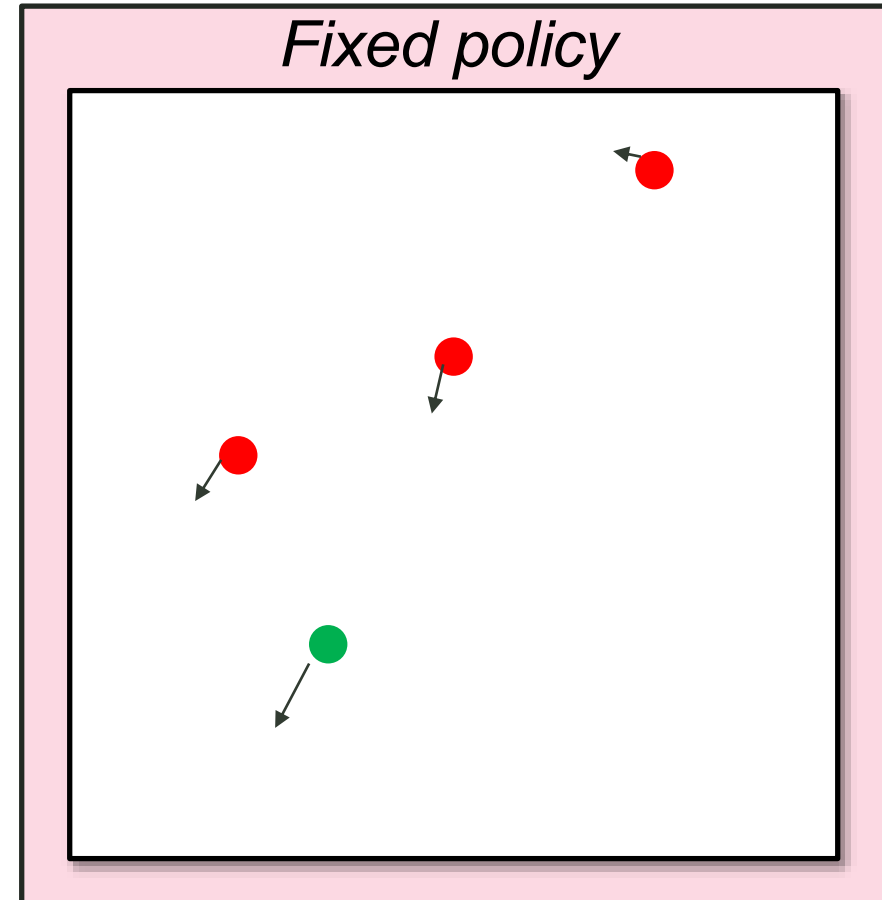
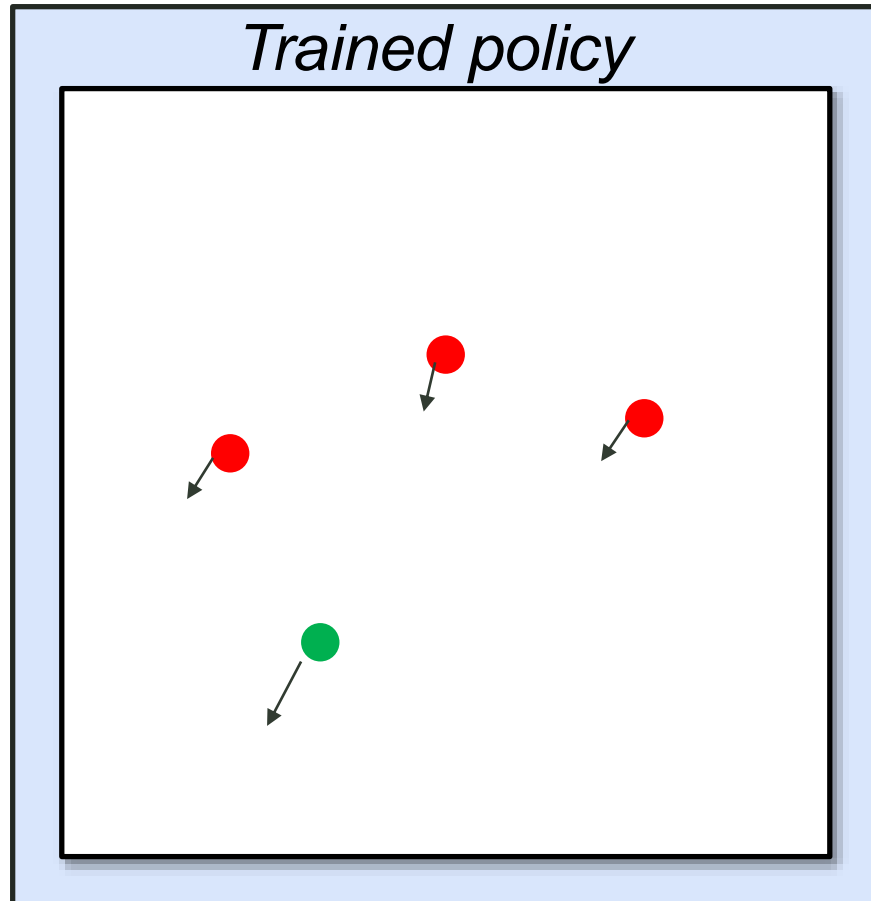


# METHOD – PREDATOR-PREY PURSUIT ENVIRONMENT





## METHOD – PREDATOR-PREY PURSUIT “STRATEGIES”

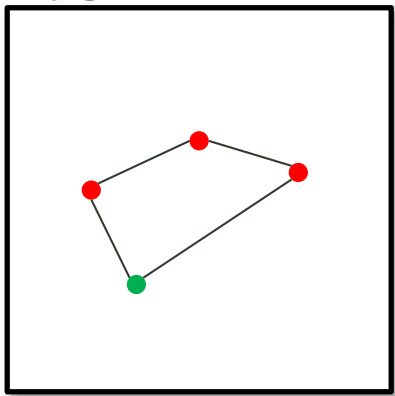




## METHOD - TIMESERIES

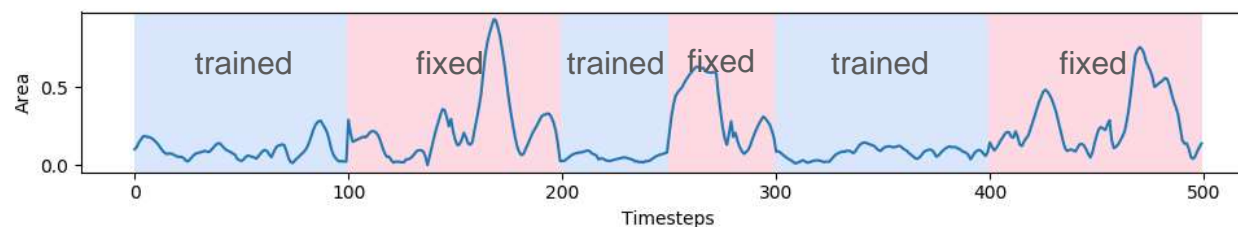


- **Polygon area**



- **Timeseries**

- Test episodes were creating by interleaving different strategies, i.e., *ground truth segments*

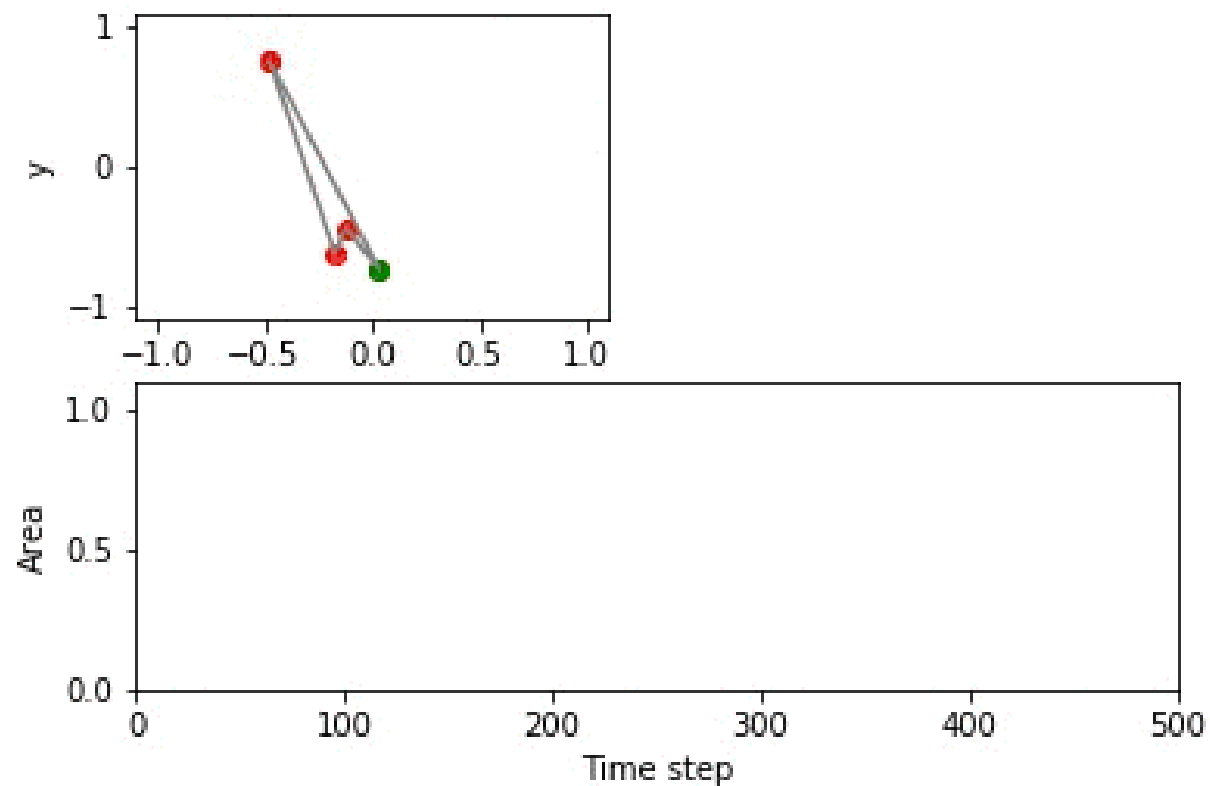




## EXAMPLE – EPISODE 2



gif shown at SPIE: <http://ezaroukian.github.io/CVmaterials/plotsCombo-interp-2.gif>



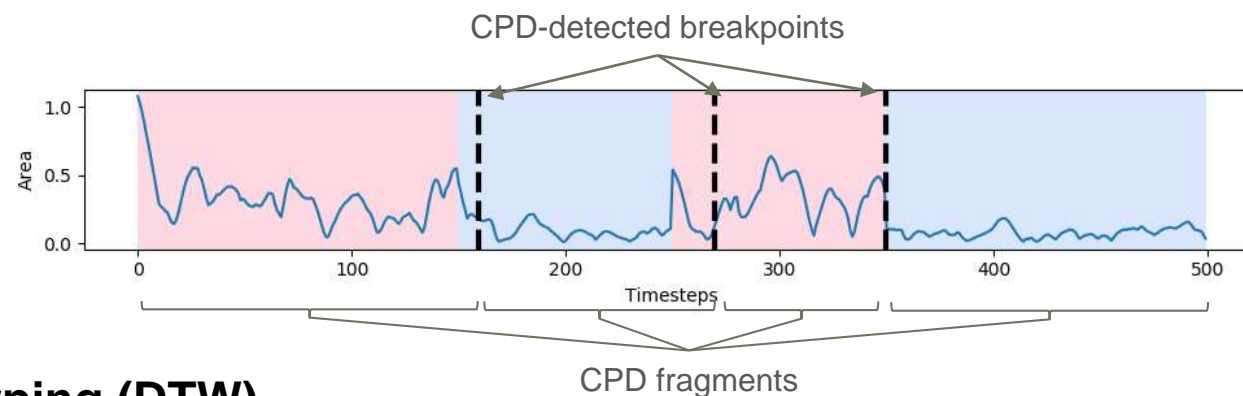


## METHOD – STRATEGY IDENTIFICATION



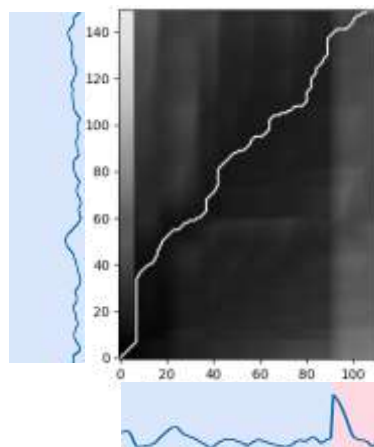
- **Change Point Detection (CPD)**

- Combination of various cost functions (mean, variance, covariance, rank, density, etc.) from different distributions of data was utilized to determine change points in the timeseries
  - Divide data into *CPD fragments*, which can be compared to ground truth segments



- **Dynamic Time Warping (DTW)**

- Compare similarities between pairs of timeseries (CPD fragments).



DTW similarity scores

Fragment	2	3	4
1			
2			x
3			



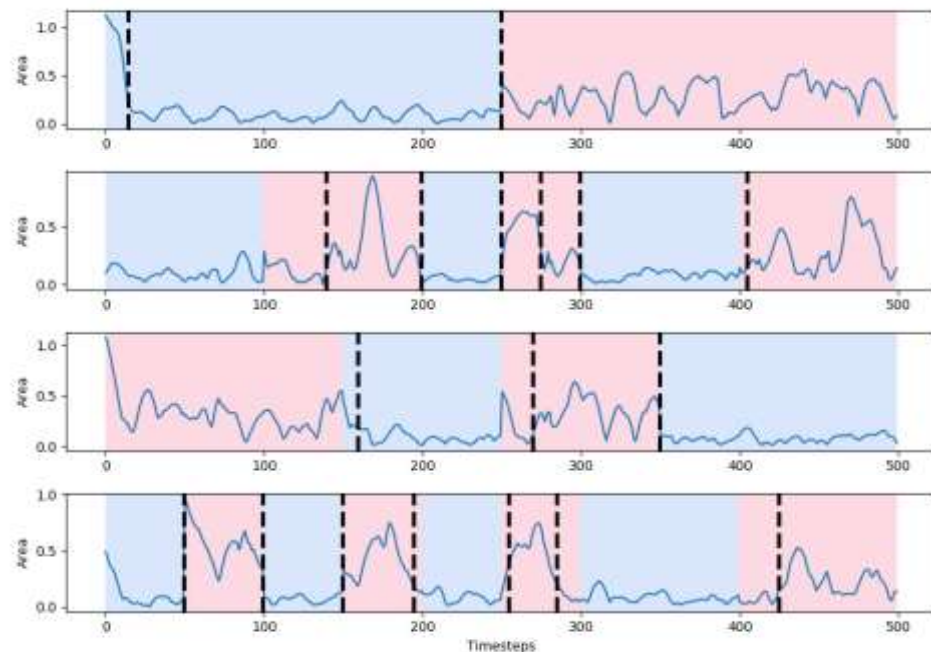


# RESULTS



## • CPD

- Metrics comparing ground truth to CPD breakpoints



	Precision, Recall 20 timestep margin	Rand index	Hausdorff distance (/500)
<b>Episode 1</b>	0.50, 1.0	0.97	235 (47%)
<b>Episode 2</b>	0.67, 0.80	0.94	40 (8%)
<b>Episode 3</b>	0.67, 0.67	0.95	20 (4%)
<b>Episode 4</b>	0.85, 0.85	0.94	25 (5%)

## • DTW

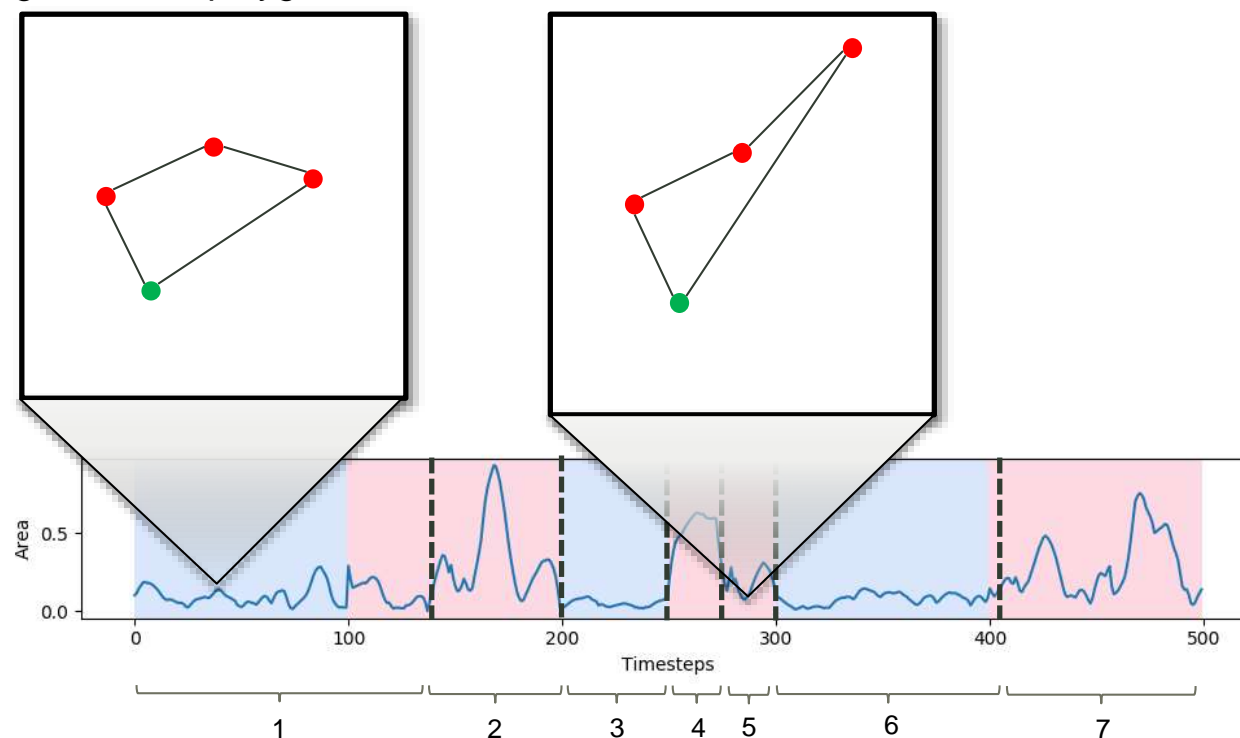
- Similarity scores between same-strategy CPD fragments (median = 0.96) > different-strategy CPD fragments (median = 0.90, Mann-Whitney U = 675, n = 58, p < 0.001, r = 0.55).



## DISCUSSION



- **Our goal:** Identify and label the implicit human strategies → Facilitate transparency, promote trust, and provide a better understanding of how humans work together and how computational teammates can be trained to fit into a human-human dynamic.
  - Using timeseries techniques, multi-agent predator-prey pursuit task and policy as ground truth
    - Represent group configuration as polygon area
    - Split with CPD
    - Classify with DTW



Fragment	2	3	4	5	6	7
1						
2						
3						
4						
5						
6						



## DISCUSSION



- **Limitations**

- How well will this method work
  - When obstacles are introduced to the predator-prey environment?
  - When human teammates are introduced?
- What information goes into the timeseries
  - Polygon area loses information, try dynamic factor analysis
  - May depend on strategies
- CPD
  - Cost
  - Sampling rate / quantity of data
- DTW
  - High similarity for *different* strategies!
- If strategies are unobservable, how useful is comparison to “ground truth” (policies)?

- **Extensions**

- t-distributed stochastic neighbor embedding (TSNE)
  - How specific behaviors are linked to the activations of the network → Do strategy/policy changes map to changes in NN activation?
- Information Theoretic Disentanglement
  - Can strategy be disentangled via deep NN?



# THANK YOU



- **Thanks to Sebastian S. Rodriguez, Sean L. Barton, James A. Schaffer, Brandon Perelman, Nicholas R. Waytowich, Blaine Hoffman, Derrik E. Asher, and Jonathan Z. Bakdash**





# DTW SIMILARITY SCORES



Episode 1 Fragment	2	3
1	0.81	0.87
2		0.93

Episode 2 Fragment	2	3	4	5	6	7
1	0.93	0.97	0.86	0.96	0.98	0.95
2		0.86	0.92	0.91	0.90	0.97
3			0.79	0.94	0.99	0.87
4				0.86	0.84	0.93
5					0.97	0.92
6						0.91

Episode 3 Fragment	2	3	4
1	0.91	0.95	0.90
2		0.92	0.99
3			0.91

Episode 4 Fragment	2	3	4	5	6	7	8
1	0.82	0.97	0.88	0.97	0.89	0.98	0.95
2		0.76	0.92	0.82	0.93	0.81	0.88
3			0.82	0.98	0.79	0.98	0.91
4				0.89	0.97	0.86	0.95
5					0.82	0.98	0.94
6						0.83	0.93
7							0.96